



24 mai 2012

FRAM for ANTICIPATION FRAM based ecology of action simulation – application to ATM





Expected

New technology, new regulation, new organisation, etc.

Change

Transition from a state to another

Unexpected

Automation degradation,abnormal human variability, abnormal situation, etc.



Expected

New technology, new regulation, new organisation, etc.

Change

Transition from a state to another

Ecology of Change

Given the multiple interactions and feedbacks within the environment in which they take place, change, once started, often are beyond the control of the system, causing unexpected and sometimes even contrary effects to those expected. (adapted from morin 1990)

Unexpected

Automation degradation,abnormal human variability, abnormal situation, etc.







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Research questions

Model LSSTS in a perspective of assessing consequences of change impact (performances affected, intensity, propagation)



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Context	AMAN degradation impacts on ATM performances	
Model	TMA resilience performance	
Tool	FRAM consequence of event analysis	



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Context	AMAN degradation impacts on ATM performances
Model	TMA resilience performance
Tool	FRAM consequence of change analysis



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Context

AMAN degradation impacts on ATM performances





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Context

AMAN degradation impacts on ATM performances



Calculate optimum aircraft arrival sequences and times for flights approaching to defined constraint points

Presente the planned inbound traffic flow at the controller working positions together with suitably generated advisories in order to meet the planned arrival sequence and time schedules.



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Context

AMAN degradation impacts on ATM performances



Temporary malfunctionning

Provide misleading information

Permanent malfunction



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Context	AMAN degradation impacts on ATM performances
Model	TMA resilience performance
Tool	FRAM consequence of change analysis

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Intrinsic ability of a system to adjust its functioning prior to, during, or following changes and disturbances, so that it can sustain required operations under both expected and unexpected conditions (Hollnagel 2011).

Respond to regular and irregular conditions in an effective, flexible manner

Learn from past events, understand correctly what happened and why

Monitor short-term developments and threats; revise risk models

Anticipate long-term threats and opportunities

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Respond to regular and irregular conditions in an effective, flexible manner





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Respond to regular and irregular conditions in an effective, flexible manner

1 - Detect situation
5 - Mobilize resources to respond
4 - Plan response
2 - Identify situation
3 - Evaluate situation

Control Mode

Strategic	In the strategic control mode correspond, system as a time horizon and can look ahead at higher level goals.
Tactical	The tactical control mode corresponds to situations where performance more or less follows a known procedure or a rule
Opportunistic	In the opportunistic control mode, the salient features of the current context determine the next action
Scrambled	random



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TMA regular control process





Control flight position and speed and clear pilot in order that it follows planed arrival sequence.

Control distance between aircrafts and clear pilots if minimum distance between aircraft is not satisfied

Control flight position and evolution in order to avoid potential conflict



TMA regular control process





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Control traffic simple model

Hypothesis 1.

Control traffic performance is model with EXC_TMA *Monitor traffic* function and *Clear Pilot* and AMAN functions *Compute and Display SEQ_LIST* and *Compute and Display advisories*.



Control traffic simple model



Factors that affect Monitor traffic function can affect **available time** to monitor traffic and clear pilot and others can affect **time required** by EXC_TMA to achieve functions.

Endogenous factors

EXC_TMA variability factors (workload, stress, experience in monitoring traffic, experience with AMAN) will affect EXC_TMA time to proceed

EXC_TMA focus of attention impact time available (if EXC_TMA focus on monitoring traffic he's got more time than if he focus both on monitoring traffic, distance separation and emergence situations)

Exogenous factors

Complexity of traffic and amount of traffic affects available time because of the frequency of occurrence of new AMAN advisories.

Working conditions impacts both available time and time required to perform

Coupling factors

Availability of AMAN impacts available time. If AMAN is available control functions *Detect, Identify, Evaluate* and *Plan* are "negligible" because of the automation. If AMAN is not available those function have to be done manually and then impact *time available*.

Control traffic variability hypothesis



In strategic control mode time required to perform functions is much superior to available time :

Strategic

EXC TMA variability factors are optimum EXC TMA is focusing half of it's activity on Monitor traffic function AMAN is available Complexity of traffic and amount of traffic is low

In tactical control mode time required to perform functions is just superior to available time :

EXC_TMA variability factors are not optimum

Tactical

OR EXC TMA is focusing less than half of it's activity on *Monitor traffic* function OR Complexity of traffic and amount of traffic is medium AND AMAN is available

Control traffic variability hypothesis





Opportunistic

In to opportunistic control mode time required to perform functions is inferior to available time :

AMAN is not available and other conditions are optimum or average AMAN is available and others conditions are negative



In to scrambled control mode time required to perform functions is much inferior to available time :

AMAN is not available and other conditions are negative

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Control traffic variability model



Endogenous factors of variability		
Habit to AMAN	[High(10), Medium (5), Low (0)]	
Training	[High(10), Medium (5), Low (0)]	
Workload	[High(10), Medium (5), Low (0)]	
Stress	[High(10), Medium (5), Low (0)]	
Focus of attention	[High(10), Medium (5), Low (0)]	
Number of tasks	[High(10), Medium (5), Low (0)]	

Endo	aenous	variability	v V <i>en</i> eva	luation
			,	

lf	10 >=	$(\Sigma \text{ factors } / 6) > 7$	then	V <i>en</i> = Optimum
lf	7 >=	$(\Sigma \text{ factors } / 6) > 3$	then	Ven = Average
lf	3 >=	$(\Sigma \text{ factors } / 6) > 0$	then	V <i>en</i> = Bad

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Control traffic variability model

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Exogenous factors of variability			
Working conditions	[High(10), Medium (5), Low (0)]		
Complexity of traffic	[High(10), Medium (5), Low (0)]		
Amount of traffic	[High(10), Medium (5), Low (0)]		

Exogenous variability Vex evaluation					
lf	10) >=	$(\Sigma \text{ factors } /3) > 7$	then	V <i>ex</i> = Optimum
lf	7	>=	$(\Sigma \text{ factors } / 3) > 3$	then	Vex = Average
lf	3	>=	$(\Sigma \text{ factors } / 3) > 0$	then	Vex = Bad



Control traffic variability model

M//	
CDC	
CKC	

Coupling factors of variability			
AMAN available	[Yes, No]		

Coupling variability Vco evaluation

- If Yes V*co* = Optimum
- If No Vco = bad

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Control traffic variability model

Control traffic variability model control mode calculation rules

IF (Ven == Optimum) AND (Vex == Optimum) AND (Vco == Optimum) THEN Control Mode = Strategic

IF (Ven == Average) OR (Vex == Average) AND (Vco == Optimum) THEN Control Mode = Tactical

IF ((Vco == Optimum) AND ((Ven == bad) AND (Vex == bad)) OR ((Vco == bad) AND ((Ven != bad) AND (Vex != bad)) THEN Control Mode = Opportunistic

IF ((Vco == bad) AND ((Ven == bad) OR (Vex == bad)) THEN Control Mode = Scrambled



Control traffic variability model

Consequences of variability of control mode on EXC_TMA endogenous variability and on *monitor traffic* function.

1.If control mode is strategic, there is no influence on EXC_TMA variability and on the performance of the function, time to perform and precision are optimum

2.If control mode is tactical EXC_TMA stress is affected to medium and time to perform and precision are average

3.If control mode is opportunistic EXC_TMA stress and workload are affected to medium and time to perform and precision are average

4.If control mode is scrambled EXC_TMA stress and workload are affected to high and time to perform and precision are bad

Conclusion



Next steps :

Modeling and couping all TMA control activities Modeling of global varibaility of TMA Modeling and coupling varibaility of TWR and ACC to TMA variability

Link FRAM based model with Lindemayer System based model Develop prototype of simulation tool

Generalyse methodology